Integration of Motor and Visual Information in the Parietal Area 5 During Locomotion

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Beloozerova, Irina N. and Mikhail G. Sirota. Integration of motor and visual information in the parietal area 5 during locomotion. J Neurophysiol 90: 961–971, 2003; 10.1152/jn.01147.2002. The parietal cortex receives both visual- and motor-related information and is believed to be one of the sites of visuo-motor coordination. This study for the first time characterizes integration of visual and motor information in activity of neurons of parietal area 5 during locomotion under conditions that require visuo-motor coordination. The activity of neurons was recorded in cats during walking on a flat surface—a task with no visuo-motor coordination required (flat locomotion), walking along a horizontal ladder or a series of barriers—a task requiring visuo-motor coordination for an accurate foot placement on surface that is heterogeneous along the direction of progression (ladder and barriers locomotion), and walking along a narrow pathway—a task requiring visuo-motor coordination on surface homogeneous along the direction of progression (narrow locomotion). During flat locomotion, activity of 66% of the neurons was modulated in rhythm of stepping, usually with one peak per cycle. During ladder and barrier locomotion, the proportion of rhythmically active neurons significantly increased, their modulation became stronger, and the majority of neurons had two peaks of activity per cycle. During narrow locomotion, however, the activity of neurons was similar to that during flat locomotion. We concluded that, during locomotion, parietal area 5 integrates two types of information: signals about the activity of basic locomotion mechanisms and signals about heterogeneity of the surface along the direction of progression. We describe here the modes of integration of these two types of information during locomotion.

INTRODUCTION

Many studies provide evidence that the parietal cortex is involved in the control of limb movements in extrapersonal space (see Andersen et al. 1997; Mountcastle 1995 for review). Visual information and visuo-motor coordination play an important role in this control. Despite the considerable amount of data on the activity of neurons in the parietal cortex during different motor tasks, the neuronal mechanisms by which visual information affects motor commands, as well as the principles of visuo-motor coordination are not well understood. The goal of this study was to characterize the activity of neurons in parietal area 5 during locomotion under conditions that require visuo-motor coordination.


It was suggested that neuronal control of natural locomotion with precise stepping uses the same neuronal machinery that is employed during reaching movements (Georgopoulos and Grillner 1989). To walk in natural environments, a subject has to watch the steps because the support surface is usually uneven. Visual information about the surface structure allows the subject to perform necessary adjustments of stepping. Thus natural locomotion involves two essentially different neural mechanisms. First, basic rhythmic pattern of muscle contractions for each limb is generated by the spinal cord (Forsberg et al. 1980a,b; Grillner and Zangger 1979; Sherrington 1906, 1910; for review, see Orlovsky et al. 1999). Second, the adaptations of this basic pattern to the features of natural supporting surfaces are accomplished by supra-spinal mechanisms. It was shown, for example, that the activity of the motor cortex changes substantially when cats overstep obstacles or place paws precisely on cross-pieces of a horizontal ladder during locomotion (Armstrong and Drew 1984; Beloozerova and Sirota 1993; Drew 1993; Widajewicz et al. 1994).

In the present study, we recorded the activity of neurons in area 5 in cats during three locomotion tasks: walking on a flat surface—a task with no visuo-motor coordination required (flat locomotion), walking on a horizontal ladder or overstepping a series of barriers—a task requiring visuo-motor coordination for accurate foot placement on a surface heterogeneous along the direction of progression (ladder and barriers locomotion), and walking along a narrow pathway—a task requiring visuo-motor coordination for accurate foot placement on a surface homogeneous along the direction of progression (narrow locomotion). Comparison of neuronal discharges during these locomotion tasks provided evidence that neurons in area 5 of...
parietal cortex receive information about the activity of basic locomotion mechanisms and information about the heterogeneity of the supporting surface along the axis of progression. We describe here the modes of integration of these two types of information in the discharge patterns of area 5 neurons.

Some of the results have been reported in brief (Beloozerova and Sirota 1992).

METHODS

Recordings were obtained from three adult cats (a male and 2 females). Some of the methods have been described (Beloozerova and Sirota 1993; Beloozerova et al. 2003) and will be reported briefly here. All experiments were conducted with the approval of the Barrow Neurological Institute Animal Care and Use Committee.

Experimental design

Positive reinforcement (food) was used to adapt cats to the experimental situation and to induce locomotion (Pryor 1975). A box 2.5 m long and 0.5 m wide served as an experimental chamber. A longitudinal wall divided the box into two corridors that cats passed sequentially and repeatedly. In one of the corridors, the floor was flat, and a horizontal ladder, barriers (Fig. 1A), or longitudinal dividers (Fig. 1B) were placed in the other. The cross-pieces of the horizontal ladder were flat and 5 cm wide. The width of the cross-pieces was chosen to exceed the cat’s mean foot length that equals 3.5 mm, so that cats had a full foot support on a crosspiece. Cross-pieces of the ladder were spaced 25 cm apart, that is, at half of the mean step length observed during flat locomotion (Beloozerova and Sirota 1993), and were elevated 8 cm above the ground. Barriers were 7 cm high and 1 cm thick and were also placed 25 cm apart. The width of the narrow walkway was 5 cm. The passage of a cat through the beginning or the end of each corridor was monitored using infrared photodiodes.

Surgical procedures

Surgery was performed under isoflurane anesthesia using aseptic procedures. The skin and fascia were removed from much of the dorsal surface of the skull. At 10 points around the circumference of the head, stainless steel screws were screwed into the skull and connected together with a wire; the screw heads and the wire were then inserted into a plastic cast to form a circular base. Later, awake cats were rigidly held by this base while searching for neurons before a locomotion test. The base was also used later for fixation of connectors, a miniature microdrive, and a protective and electrically shielding cap. A portion of os parietale and the dura above parietal area 5 over ~1.0 sq cm were removed. The area 5 region was visually identified by the surface features. The aperture was then covered by a 1-mm-thick plastic plate in which holes 0.36 mm in diameter had been drilled and filled by sterile wax. The plate was fastened to the surrounding bone with orthodontic resin (Densply Caulk).

Single-unit recording and neurons sampled

Sampling of neurons began several days after the surgery. The cat was positioned on a table, and the base that was attached to its skull during the surgery was fixed in the frame so that the head was immobilized while the body was put in a comfortable position. Methods ensuring the humane treatment of subjects during immobilization of the head have been described (Beloozerova and Sirota 1993; Beloozerova et al. 2003).

Neuronal activity was recorded extracellularly using either a conventional tungsten-varnish-insulated (50–125 μm OD) microelectrode or a quartz-insulated microelectrode with platinum-tungsten core (40 μm OD) (Reitboeck 1983). The electrode was advanced into cortical tissue through holes in the plastic plate above area 5. A miniature manual single-axis micromanipulator, rigidly fixed to the base, was used to lower the electrode. Positions of tracks from which the activity of neurons was sampled is shown by dots on a schematic drawing of the brain (dorsal view). D: a sample record of a neuron’s discharge during flat and ladder locomotion. Bottom: the swing (Sw, deflection up) and stance (St, deflection down) phases of the step cycle of the forelimb contralateral to the recording site in the cortex recorded by an electrical sensor.

Receptive field testing

The somatic receptive fields were determined in resting animals by manual application of stimuli to the skin and hair, by palpation of muscles and their tendons, and by passive movements of joints. The

FIG. 1. Experimental design. A: the experimental box was divided into two corridors each 2.5 m long and 0.5 m wide. A horizontal ladder or longitudinal dividers were placed in 1 corridor. Cats were trained to pass sequentially and repeatedly through the corridors. B: on the cross-pieces of the ladder and in between the barriers schematically show placements of cat forelimbs. C: positions of tracks from which the activity of neurons was sampled is shown by dots on a schematic drawing of the brain (dorsal view). D: a sample record of a neuron’s discharge during flat and ladder locomotion. Bottom: the swing (Sw, deflection up) and stance (St, deflection down) phases of the step cycle of the forelimb contralateral to the recording site in the cortex recorded by an electrical sensor.
responses to visual stimulation were tested with the head restrained by
switching the lights on-off by presenting stable and moving stimuli:
two-dimensional circles 2.5 cm in diameter, stripes 5 cm wide and 100
cm long, fields 50 × 50 cm, and complex three-dimensional stimuli:
bars as those that were used for cross-pieces on the ladder, toys, pieces
of food, hands. Two-dimensional stimuli were black and were pre-
äsent presented against a white screen that was positioned 50 cm in front of the
animal. Stripes and fields were oriented horizontal, vertical, or diag-
onal. Eight directions of planar movements were tested: left-right,
up-down, and four diagonal directions. In addition, while an object
was inside the receptive field of a neuron, the screen was moved back
and forward in the range of 25–75 cm in front of the animal. Complex
three-dimensional stimuli were presented against the natural labora-
tory background and were moved in different directions in the frontal
plane at the distance of ~50 cm in front of the animal and also toward
the animal and away from it. Speed of all stimuli movements was in
the range of 0.5–1.0 m/s, which is in the range of the speed of
locomotion that cats used inside the experimental chamber.

Processing of neuronal activity

The position and size of receptive fields was determined by listen-
ing to the audio monitor and measuring the entire area from which
action potentials could be elicited. A directional selectivity was ac-

c
c
boxed by comparing the number of spikes elicited by stimulation in
different directions. During locomotion, the duration of swing and
stance phases of each step of the forelimb contralateral to the cortical
area under study was recorded using an electrical sensor (Beloozerova
and Sirota 1993). To accomplish this, a thin rubber sack was placed on
the cat’s forelimb, a thin metal electrode was attached to the external
surface of the sack under the foot, and a voltage of 2–5 mV was
applied to the electrode. The floor of the experimental box was
covered by a cloth moistened with 0.1% sodium chloride to make
the surface electrically conductive. A wire, sewn into the cloth along the
length of the box, was connected to the common ground. The fall of
time result from the contact of the foot with the floor was recorded.
The start and finish of electrical contact was taken as the start and
finish of the stance phase of a step and, in selected experiments, was
verified using simultaneous video recording. The onset of the swing
phase was taken as the beginning of the step cycle. The duration of
each step cycle was divided into 10 equal bins, and the number of
spikes in each bin was counted. The discharge frequency in a bin was
derived according to the method of Udo et al. (1982) that averages the
instantaneous frequency of inter-spike intervals that fall within the bin
and also accounts for those intervals that overlap with bin’s beginning
and end. The frequency histograms were smoothed using moving filter
with a span of three bins. The following parameters were calculated
for each neuron: the mean discharge frequency; the coefficient of
modulation (M) defined as

\[ M = (1 - \frac{F_{\text{min}}}{F_{\text{max}}}) \times 100\% , \]

where \( F_{\text{min}} \) and \( F_{\text{max}} \) are the minimal and the maximal frequencies of
discharge in the histogram; and the position of the burst of activity,
which was defined as the portion of the cycle where the activity
exceeded the minimum by 25% of the difference between the maxi-
mal and minimal frequencies in the histogram. The beginning and end
of a burst was rounded to the nearest bin beginning/end.

Statistical procedures

Parametric tests were used when possible for comparisons between
groups. Unless noted otherwise, for all mean values, the SE is given.
The discharge frequency and modulation of neurons during different
tasks was compared using paired samples t-test. When data were
categorical, nonparametric \( \chi^2 \) or Mann-Whitney \( U \) tests were used.

Histological procedures

At the termination of the experiment, cats were deeply anesthetized
with pentobarbital sodium and several reference electrolytic lesions
were made in the area of recording. Cats were perfused with isotonic
saline followed by a 10% Formalin solution. Frozen sections of
50-μm thickness were cut in the recording region. The tissue was
stained for Nissl substance with cresyl violet. Positions of tracks in the
cortex were estimated in relation to the reference lesions.

RESULTS

Role of vision in locomotion tasks tested

We evaluated the involvement of vision in performance of
locomotion tasks that we used for our experiments by testing
the ability of cats to do these tasks in the complete darkness.
Figure 2A shows the stepping pattern of a cat during walking
along the horizontal ladder (ladder locomotion) and then dur-

ing walking on the flat surface (flat locomotion) in an illumin-
ated room. During the passage, the cat walked faster on the
flat surface than on the ladder; however, the stepping patterns
each walk were rather regular. In the second trial (Fig. 2B),
the lights were turned off when the cat entered the corridor with
flat surface. On the flat surface, the cat stepped regularly
in the dark and successfully reached the feeding rack. Thus
vision was not necessary for flat locomotion. In contrast, when
the lights were turned off while the cat was on the ladder in the
third trial (Fig. 2C), locomotion was arrested: the cat did not
place the foot on a support until after the lights were back on.
Thus ladder locomotion required visual control of stepping.
A cessation of locomotion was also observed in the fourth trial
when the lights were turned off while the cat was in the

corridor with barriers (Fig. 2D). Barriers locomotion did also
require visual control of stepping. Walking along a narrow
pathway (narrow locomotion) was possible, although irregular
and greatly slowed in the dark (Fig. 2D). Thus narrow loco-

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definition as the portion of the cycle where the activity

System of the experiments.

\[ \text{Sw} \]

\[ \text{St} \]

\[ \text{I} \]

\[ \text{A} \]

\[ \text{B} \]

\[ \text{C} \]

\[ \text{D} \]

\[ \text{E} \]

\[ \text{F} \]

\[ \text{G} \]

\[ \text{H} \]

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\[ \text{J} \]

\[ \text{K} \]

\[ \text{L} \]

\[ \text{M} \]

\[ \text{N} \]

\[ \text{O} \]

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\[ \text{T} \]

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sation for the loss of vision was possible, probably by the use of somatosensory cues.

Activity of neurons during locomotion on the flat surface

The activity of 137 neurons was recorded during locomotion on the flat surface (flat locomotion). The mean speed of flat locomotion across the cats was $0.65 \pm 0.14$ (SD) m/s, and the step coefficient (the portion of swing phase in the step cycle) was $42 \pm 1\%$. On transition from standing to locomotion, the discharge rate of many neurons increased, so the mean discharge rate for the whole population during locomotion was higher than that during standing ($21.6 \pm 1.7$ vs. $16.3 \pm 1.2$ imp/s; $P < 0.01$, paired-samples t-test). During flat locomotion, the activity of 66% of all recorded neurons was modulated in the stepping rhythm; that is, the activity was higher in one phase of the step and lower in another phase (Fig. 3, A and B). The coefficient of modulation ($M$) was on average $58 \pm 2\%$. Three patterns of modulation were observed. Among all recorded neurons, $27\%$ had one peak of activity during step cycle (as the neuron in Fig. 3A), $19\%$ had one trough (as the neuron in Fig. 3B), and $20\%$ had two peaks (as the neuron in Fig. 3C). The neurons with one peak and one trough will be considered together in this paper and will be referred to collectively as "one-peak" neurons (Fig. 3D). The bursts of activity of different neurons were distributed slightly unevenly over the step cycle. The bursts of some more neurons started around the beginning of swing and were well aligned to it (Fig. 3E). The mean duration of the bursts in this group was $30 \pm 1\%$ of the cycle. The bursts of somewhat smaller fraction of neurons started later in the cycle and were distributed with a more variable onset throughout the late swing and stance phases (Fig. 3E). In contrast to the bursts of neurons from the first group, the duration of bursts in these neurons on average was longer ($55 \pm 3\%$ of the cycle; $P < 0.001$, U test). The histogram of the mean frequencies of all step-related neurons had a weak peak during the swing phase (Fig. 3F).

Activity of neurons during locomotion on the ladder

On the horizontal ladder the surface was significantly heterogeneous along the direction of progression. During walking along the ladder (ladder locomotion), each limb overstepped two gaps and every other cross-piece of the ladder. The footprints of the two forelimbs are schematically shown in Fig. 1A as open circles on the cross-pieces of the ladder. The mean speed of ladder locomotion was $0.58 \pm 0.07$ (SD) m/s, and the step coefficient was $39 \pm 1\%$.

All 137 neurons that were studied during flat locomotion were also studied during ladder locomotion. Three typical examples of the activity of neurons during flat and ladder locomotion are presented in Fig. 4. The activity of the neuron shown in A was not step-related during flat locomotion but had a double-peak discharge pattern during ladder locomotion. The neuron shown in B had one peak of activity during flat locomotion and two peaks during ladder locomotion, with each of the peaks being higher than that during flat locomotion. The neuron shown in C had two peaks during flat locomotion, and this discharge pattern became even more pronounced during ladder locomotion.

The discharge rate of 55% of neurons increased on transition from flat to ladder locomotion, and the mean discharge rate of the whole population was higher during ladder locomotion as compared with flat locomotion ($29.1 \pm 2.6$ vs. $21.6 \pm 1.7$ imp/s; $P < 0.01$, U test). The fraction of modulated neurons was larger during ladder than during flat locomotion ($93 \pm 66\%$; $P < 0.01$, $\chi^2$ test). The average $M$ also increased ($82 \pm 2$ vs. $58 \pm 2\%$; $P < 0.001$, U test), as did the proportion of the double-peak neurons ($84\%$ vs. $20\%$; $P < 0.001$. $\chi^2$ test; Figs. 3D and 5A). In the double-peak neurons, one peak usually occurred in swing, and the other one in stance phase (Fig. 5B). The two bursts of activity were on average of an approximately similar duration, occupying $30 \pm 1\%$ of the step cycle each. In
Addition, in one half of these neurons (28/57), the activity during ladder locomotion (as in cell in Fig. 4B of 57/63) of these neurons there appeared a second peak of single-peak one.

N FLAT LOCOMOTION, N = 47 (27% OF THE TOTAL SAMPLE). All these neurons retained their double-peak discharge pattern during ladder locomotion as did the cell in Fig. 4C. The phase positions of the peaks in all but one of these cells remained unchanged.

Activity of neurons during stepping over a series of barriers

Although the width of the cross-pieces of the ladder exceeded the length of cat’s foot by ~1.5 cm, we did an experiment to find out whether the differences in activity of the neurons during flat and ladder locomotion were due to the different requirements for the body stabilization during these two locomotion tasks. We presented cats with a walkway partitioned with a series of barriers. With the barriers, the surface of the corridor was significantly heterogeneous along the direction of progression, as it was on the ladder; however, the supporting surface was very wide (25 sq cm), thus the requirement for the body stabilization was similar to that during flat locomotion. During walking through a series of barriers (barriers locomotion), each limb overstepped two successive barriers and every other gap between them (Fig. 1A). The mean speed of barriers locomotion was 0.65 ± 0.15 (SD) m/s, and the step coefficient was 44 ± 1%.

Of 137 neurons recorded during flat and ladder locomotion, the activity of 47 neurons was also recorded during barriers locomotion. Figure 6, A–D, shows two typical examples of the activity of neurons during flat and barriers locomotion. The activity of the first neuron (A and B) was not step-related during flat locomotion (A) but had a clear-cut modulation with a two-peak pattern during barriers locomotion (B). The activity of the second neuron (C and D) had one peak per cycle during flat locomotion (C), and two peaks during barriers locomotion, each of which being higher than that during flat locomotion (D).

On transition from flat to barriers locomotion, the discharge rate of a large number of neurons (43%) increased as it did on transition to ladder locomotion, although in this case the mean activity increase for the whole population did not reach the level of statistical significance (24.4 ± 3.0 imp/s as compared with 21.6 ± 1.7 imp/s during flat locomotion). The fraction of modulated neurons was larger during barriers than during flat locomotion (87 vs. 66%; P < 0.01, χ² test). The average M was also larger (83 ± 2 vs. 58 ± 2%; P < 0.001, U test), as was the proportion of the double-peak neurons (70 vs. 20%; P < 0.001, χ² test; Figs. 6E and 3D). All the preceding parameters were similar to those found during ladder locomotion. Although the beginnings of the activity bursts were more variable during barriers than during ladder locomotion, the predominantly double peak discharge pattern during barriers locomotion was also reflected in the histogram of the mean frequencies of the step-related neurons (Fig. 6G). That histogram had two peaks: one in the swing and another one in the stance phase.
Activity of neurons during locomotion along the narrow walkway

In contrast to ladder and barriers locomotion, during walking along the narrow walkway (narrow locomotion), the surface on which cats stepped was homogeneous along the direction of progression. However, as during ladder and barriers locomotion, the feet had to be placed accurately on the narrow supporting surface. Thus using narrow locomotion task we could further test if the activity of area 5 neurons during locomotion depended on the precision of stepping or did it depend on irregularities in the visual scene. The mean speed of narrow locomotion was $0.57 \pm 0.08$ (SD) m/s, and the step coefficient was $43 \pm 1\%$.

Of 137 neurons recorded during flat and ladder locomotion, the activity of 45 neurons was also recorded during narrow locomotion. Figure 7, A–C, gives a typical example of the activity of a neuron in 40 steps during each flat, narrow, and ladder locomotion. The discharge frequency of the neuron during flat locomotion (A) was low, but the activity did show a step-related modulation (the cell discharged more spikes at the end of stance phase than in any other portion of the step cycle). The discharge frequency of the neuron during narrow locomotion (B) was also low, and the step-related modulation was absent. When tested during ladder locomotion (C), however, the neuron demonstrated much higher activity and a clear-cut modulation that had two peaks: one approximately coinciding with the peak observed during flat locomotion and a newly formed one in early stance.

During narrow locomotion, the mean discharge rate of the neurons was similar to that during flat locomotion ($25.0 \pm 3.2$ as compared with $21.6 \pm 1.7$ imp/s). The activity of 64% of neurons was modulated in the locomotion rhythm: 47% of them having single-peak pattern and 17% the double-peak pattern (proportions that were close to those found during flat locomotion, Figs. 7D and 3D). The average M was also similar to that during flat locomotion ($57 \pm 3$ compared to $58 \pm 2\%$). There were slightly more cells that had bursts in swing phase of the contralateral forelimb (Fig. 7E). The histogram of the mean frequencies of the step-related neurons had one peak in the swing phase (Fig. 7E). The bursts and the mean frequency distributions both were similar to those observed during flat locomotion (Fig. 3, E and F).

Activity of neurons with somato-sensory receptive fields

Somato-sensory receptive fields were found in 22% (14/64) of the neurons tested. The different receptive fields are summarized in Table 1.

During flat locomotion, the activity of only seven (50%) neurons with somatosensory receptive fields was step-related (Table 1), and there were five single-peak and two double-peak neurons. The mean frequency ($19.0 \pm 4.9$ imp/s) and the average M ($59 \pm 5\%$) of these neurons were similar to those of the nonsomatosensory responsive ones ($20.3 \pm 1.7$ imp/s and $58 \pm 2\%$, respectively). In six neurons, a peak of activity...
occurred during swing phase of the contralateral forelimb. The activity of more than half of the neurons with receptive fields on the forelimb as well as both neurons with receptive fields on the neck was not step-related (Table 1).

During ladder locomotion, the activity of 12 (86%) neurons with somatosensory receptive fields was step-related (Table 1), and there were three single-peak and nine double-peak neurons. The mean activity (23.9 ± 4.8 imp/s) and the average M (87 ± 4%) of these neurons were again similar to those of the nonsomatosensory responsive ones (26.8 ± 2.5 imp/s and 82 ± 2%, respectively). In nine neurons, a peak of activity occurred during swing phase of the contralateral forelimb, and if there were two peaks, the one in the swing phase was the strongest one. The activity of one neuron with receptive field on the forelimb was still not step-related (Table 1).

Visual receptive fields were found in 20% (17/83) of the neurons tested. In all of these neurons, responses to lights ON-OFF and to stationary stimuli were weak or absent, however, all of the neurons responded well to moving stimuli. The receptive fields of all cells were excitatory and were located in the lower portion of the visual field in front of the animal. Except for three, all neurons responded to simple stimuli (black circles, stripes, or fields) moving in the frontal plane. Most neurons showed little or no directional selectivity in the frontal plane; however, all of them discharged more vigorously in response to approaching stimuli as compared with receding ones. All neurons responded to complex stimuli (bars, hands, toys, or food) with the approaching direction of their movement being the strongest stimulus.

At rest the activity of the visually responsive neurons was similar to that of the nonvisually responsive ones. With the start of locomotion, however, the activity of the visually responsive neurons decreased and during flat locomotion was...
lower than that of the nonvisually responsive ones (8.5 ± 2.0 vs. 21.3 ± 1.7 imp/s; P < 0.0001, U test). The activity of 60% of the visually responsive neurons was related to the locomotion cycle with an average M of 59 ± 6%, a value similar to that of the nonvisually responsive neurons (59 ± 3%). All of the visually responsive neurons had one peak of activity per step cycle, and in all of them, that peak occurred in the swing phase of the contralateral forelimb.

During ladder locomotion, the visually responsive neurons retained their low activity. The activity of 80% of them was modulated in the locomotion cycle; however, the average M was lower than that of the nonvisually responsive neurons (78 ± 4 vs. 82 ± 2%; P = 0.05, U test). Like the nonvisually responsive neurons, the great majority of the visually responsive neurons had two peaks of activity per step cycle. The phase distribution of the peaks of activity of the neurons with visual receptive fields was similar to that of the nonvisually responsive neurons.

**DISCUSSION**

**Activity of neurons during flat locomotion—the roles of internal and peripheral information**

The first finding of the present study is that the activity of many neurons in parietal area 5 was step-related during locomotion on the flat surface, when visual control of stepping was not necessary. It can thus be concluded that area 5 receives movement-related information not only during the “high-order” arm reaching movements, but also during the “lower-order” spinoally organized locomotion.

Is the step-related activity of area 5 neurons during flat locomotion driven by somatosensory stimulation or is it driven by inputs from other motor centers? At least three facts suggest that the activation of somatosensory receptors does not importantly contribute to modulation of activity of neurons in area 5 during locomotion. First, most of the neurons with the step-related modulation of activity had no somatosensory receptive fields, at least those that we could reveal with our testing technique in resting condition. Second, the activity of four of seven neurons with somato-sensory receptive fields on the forelimb was not step-related (Table 1). Third, an extra flexion of the limbs and thus an additional activation of somatosensory receptors during overstepping series of barriers as compared with that during ladder locomotion had little effect on the activity of the neurons as they were rather similarly active and modulated during both locomotion tasks (Figs. 6 and 5). Therefore it seems probable that much like during arm reaching movements (Bioulac et al. 1999; Mountcastle et al. 1975; Seal et al. 1982, 1983), activity of area 5 during flat locomotion to a significant extent depends on the status of other motor-related brain centers and not on the status of peripheral receptors. The similarity between phase distribution of the activity of neurons in area 5 (Fig. 3E) and spinal interneurons (Orlovsky and Feldman 1972; Baev et al. 1979) suggests that spinal locomotion generator could be a source of such internal information and thus be primarily responsible for modulation of the activity of 66% of the neurons in area 5.

**Activity of neurons during ladder locomotion—the roles of surface heterogeneity, precision of stepping, body stabilization, and direct visual stimulation**

Visuo-motor coordination and, therefore supraspinal control of locomotion was required during ladder locomotion. The second finding of the present study was that the activity of neurons in area 5 was dramatically different during ladder locomotion as compared with flat locomotion. That difference was found in all of the measured parameters of the activity of most of the neurons: in the discharge rates, the coefficients of modulation, and the discharge patterns. Such pronounced differences strongly suggest that area 5 participates in visuo-motor coordination during ladder locomotion. The question arises as to with what aspects of the coordination area 5 is concerned.

Unlike the flat surface, the horizontal ladder required precise placing of feet on the support. From our previous work in the motor cortex, we know that the requirement for precise feet placing may cause a dramatic change in the activity of neurons (Beloozerova and Sirota 1993). However, for area 5, we have earlier found that this cortical area is not involved in the control of accuracy of stepping (Beloozerova and Sirota 1992). Indeed, in a test that involved overstepping a series of barriers spaced progressively more closely to each other, thus gradually imposing more strict requirements for precision of stepping, the neurons of area 5 failed to correspondingly increase their discharges.

The potentially enhanced requirements for the body stabilization during ladder locomotion comparing to those during flat locomotion were also not responsible for the difference in the neuronal activity during the two locomotion tasks. In the control barriers locomotion test, the body stabilization requirements were close to those in the flat locomotion test; however, the discharges of the neurons were very different in these two tasks (Figs. 6 and 3); in contrast, they closely resembled the ones found during ladder locomotion (Figs. 6 and 5). The body stabilization was clearly compromised during narrow locomotion due to the unusual placing of right and left feet along a single line; however, the neuronal discharges during narrow locomotion were very similar to those during flat locomotion.

We hypothesized that during ladder locomotion, the activity of area 5 is primarily concerned with the visual heterogeneity of the supporting surface rather than with the motor aspects of locomotion. To test this hypothesis, we have constructed a locomotion task that required precise placing of feet on the support but in a pathway that was visually homogeneous along the direction of progression—the task of narrow locomotion. It was found that during narrow locomotion the activity of neurons was similar to that during flat locomotion (Figs. 3 and 6). Therefore we concluded that the visual heterogeneity of the surface along the direction of progression was the main factor that modulated the activity of neurons during ladder locomotion in addition to their motor related modulation. The sub-

![Table 1](http://jn.physiology.org/)

**Table 1. Task relation of somato-sensory responsive neurons**

<table>
<thead>
<tr>
<th>Receptive Field</th>
<th>Cell Count</th>
<th>Flat Locomotion</th>
<th>Ladder Locomotion</th>
</tr>
</thead>
<tbody>
<tr>
<td>All body</td>
<td>3</td>
<td>3</td>
<td>3</td>
</tr>
<tr>
<td>Forelimb</td>
<td>7</td>
<td>3</td>
<td>6</td>
</tr>
<tr>
<td>Neck</td>
<td>2</td>
<td>0</td>
<td>2</td>
</tr>
<tr>
<td>Vibrissae</td>
<td>2</td>
<td>1</td>
<td>1</td>
</tr>
<tr>
<td>Total</td>
<td>14</td>
<td>7</td>
<td>12</td>
</tr>
</tbody>
</table>
stantially different phase distributions of neuronal activity during ladder and flat locomotion (Figs. 5B and 3E) also suggest the very different driving forces for the activity modulation during these two tasks.

On the other hand, we have to conclude that the visual responsiveness of area 5 neurons, at least that that we could reveal with our testing technique in the resting conditions, was not responsible for modulation of neuronal activity during ladder locomotion. In our sample, there were a number of neurons that had visual receptive fields in the front of the animal. However, even the highly sensitive to incoming stimuli neurons, which seemed to be well situated to detect an approach of a transverse target during locomotion (a cross-piece of the ladder), demonstrated below the average levels of activity and step-related modulation during ladder locomotion. In contrast, neurons with no visual receptive fields at rest displayed a high involvement in visuo-motor coordination during locomotion. Although visual responsiveness of the neurons may be different during locomotion as compared with resting conditions, our findings allow to hypothesize that the visual peripheral information does not play much role in modulation of the activity of neurons of area 5 during locomotion, that it is the processed visual information that affects it in this situation.

**Modes of integration of motor and visual information**

The influence of visual information on the basic locomotion rhythm during ladder locomotion was exerted on the activity of the great majority of neurons. This influence was rather diverse, however.

For 37 neurons (27% of the total sample), the activity of which was not step-related during flat locomotion but was during ladder locomotion, visual information was the main modulator of their activity on the ladder (Fig. 8A). In addition, there were 28 neurons (20% of the total sample) in which visual information during ladder locomotion caused a change in the phase position of the activity peak observed during flat locomotion (Fig. 8B).

In contrast, visual information about the support surface during ladder locomotion had a relatively small effect on the discharge pattern of 27 neurons (20% of the total sample) the activity of which had two peaks per step cycle during flat locomotion (Fig. 8C). In the activity of these cells, the movement-related pattern was the dominant one. The role of visual information was to increase the activity levels and the efficacy of the step-related modulation (the coefficient of modulation, $M$).

There were also 29 neurons (21% of the total sample) in which the peak of discharge remained in place during transition from flat to ladder locomotion while the second peak emerged in the opposite phase of the step cycle (as in the cell shown in Fig. 4B). That group of neurons can be regarded as a group of “an equal representation,” because in the activity of these neurons the motor-related modulation was present along with the visually driven modulation (Fig. 8D).

Because the activity of a majority of the neurons had two peaks per step cycle during ladder locomotion, we believe that there were two visual messages reflected in the activity of the neurons. These messages probably corresponded to the results of the visual inspection of the two successive cross-pieces of the ladder. Studies show that although humans and cats usually do not look constantly at the landing targets when they walk with an accurate stepping (Patla et al. 1996; Patla 1997; Sherk and Fowler 2000, 2001), they do make short-lasting visual inspection of them approximately two steps ahead (Patla and Vickers 2003). When the stepping task is challenging enough, however, saccades are almost always made to the next footfall target (Hollands and Marple-Horvat 2001). Obtained ahead of the time or immediately before the step, information about positions of the targets on the surface reaches area 5 and modifies activity of its neurons. The fact that the area 5 population peak of activity during all locomotion tasks occurred during swing phase of the contralateral forelimb suggests that area 5 was more concerned with the position of the footfall target for that limb than with the one for the ipsilateral limb. It remains unclear, however, if visual and motor infor-

![Fig. 8](image-url)
mation are originally integrated on the neurons of area 5 or if area 5 receives this information already integrated from another motor center, for example as an “effference copy” of a motor command.

How is the integrated visual and motor information used?

In the activity of area 5 neurons, visual information was integrated with locomotor rhythmicity by enhancing it and, in many instances, by adjusting its pattern. A question arises as to how this combined information is used for control of the limbs. To answer this question, recordings from identified efferent neurons of area 5 are required. At present we can only stress that it does not seems likely that parietal area 5 exerts its influence on the peripheral apparatus during locomotion via the motor cortex. There are at least three major features in the activity of area 5 and the motor cortex that argue against this route.

First, one of the major changes in the activity of area 5 on transition from flat to ladder locomotion is the change in the pattern of activity of most neurons from a single-peak to a double-peak pattern. As a result, the majority of neurons in area 5 have two peaks of activity per step cycle during ladder locomotion. During the same time, the predominant pattern of activity of neurons in the motor cortex is the single-peak pattern (Beloozerova and Sirota 1993; Drew 1993; Widajewicz et al. 1994). It does not seem likely that the single-peak pattern of neurons in the motor cortex is formed from the double-peak pattern of neurons in area 5.

Second, in a considerable number of neurons in area 5 the change in the pattern of activity was accompanied by a change in its phase distribution. In contrast, the characteristic feature of the activity of neurons in the motor cortex during transition from flat to ladder locomotion is the rather stable phase distribution of the activity in spite of a dramatic change in its magnitude (Beloozerova and Sirota 1993). It seems unlikely that a stable phase distribution is constructed out of a flexible one.

Finally, the activity of neurons in area 5 is not related to the precision of stepping, while the activity of neurons in the motor cortex clearly is (Beloozerova and Sirota 1993).

It seems most likely that area 5 acts independently of motor cortex imposing its direct control on spinal cord and/or other subcortical motor centers to which it projects (Asanuma 1981; Gros et al. 1978; Leichnetz et al. 1984; Murray and Coulter 1981; Wiesendanger 1981; Wiesendanger et al. 1979). For example, it was shown that the movements of the face musculature evoked by microstimulation of area 5 are independent on the motor cortex (Waters and Asanuma 1983). Thus visual information about heterogeneity of the support surface in the direction of progression that is incorporated into step-related discharges of neurons of area 5 promotes appropriate adjustments of stepping on uneven support surfaces.

There were several hypotheses proposed for the role of area 5 in the control of limb movements including the “sensory” hypothesis (Hyvarinen 1982), the “command” hypothesis (Mountcastle et al. 1975), the “planning action” hypothesis (Andersen et al. 1998), the “attention” hypothesis (Colby and Goldberg 1999), the “decision” hypothesis (Shadlen and Newsome 2001), the “reference frames transformation” hypothesis (Cohen and Andersen 2002), and others. To a large extent, the diverse roles of area 5 may be complementary to each other (Kalaska 1996) or they may depend on the behavioral task. Our findings extend knowledge about area 5 of the parietal cortex by showing for the first time how the neuronal activity of this area reflects the process of integrating information about the limb movements and the heterogeneity of the support surface during goal directed stepping.

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DISCLOSURES

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