Prolonged Quadriceps Activity Following Imposed Hip Extension: A Neurophysiological Mechanism for Stiff-Knee Gait?

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Running Title: Hip Movement Alters Gait Post-Stroke

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Abstract

Purpose: The biomechanical characteristics of stiff knee gait following neurological injury include decreased knee flexion velocity at toe-off, which may be due to exaggerated quadriceps activity. The neuromuscular mechanism underlying this abnormal activity is unclear, although hyperexcitable heteronymous reflexes may be a source of impaired coordination. The present study examines the contribution of reflex activity from hip flexors on knee extensors following stroke and its association with reduced swing phase knee flexion during walking. Methods: Twelve individuals post-stroke and 6 control subjects were positioned in supine on a Biodex dynamometer with the ankle and knee held in a static position. Isolated hip extension movements were imposed at 60, 90, and 120°/s through a 50° excursion to end-range hip extension. Reflexive responses of the rectus femoris (RF), vastus lateralis (VL), and vastus medialis (VM) were quantified during and following the imposed hip rotation. Gait analysis was also performed for all subjects in the stroke group. Results: In subjects with stroke, imposed hip extension evoked a brief reflexive response in the quadriceps, followed by a heightened level of sustained activity. The initial response was velocity dependent and was larger in the stroke vs. control group. In contrast, the prolonged response was not velocity dependent, was significantly greater in the VL and RF in subjects with stroke, and importantly, was correlated to decreased swing phase knee flexion. Conclusions: Hyperexcitable heteronymous connections from hip flexors to knee extensors appear to elicit prolonged quadriceps activity and may contribute to altered swing-phase knee kinematics following stroke.
Introduction

Following neurological injury, such as stroke, muscle activity patterns during walking are often compromised, resulting in decreased gait speed, postural instability, reduced energy efficiency, and kinematic abnormalities. Substantial efforts have therefore been made to discern the biomechanical and neuromuscular characteristics of abnormal walking patterns following neurological injury. Biomechanically, “spastic paretic stiff-legged gait” has been attributed to decreased knee flexion velocity at toe-off (Anderson et al. 2004; Goldberg et al. 2003). Knee flexion velocity typically increases rapidly during the period of double support, suggesting that events occurring during this period may be particularly critical to achieving sufficient swing phase knee flexion. Conversely, inappropriate vasti activity during the double support period is purported to be the most powerful antagonist to knee flexion velocity in people with neurologic injury (Goldberg et al. 2004); yet, despite the evidence linking inappropriate knee extensor activity with swing phase knee kinematics (Kerrigan et al. 1991), the neuromuscular mechanism responsible for generating abnormal quadriceps activity are not well understood.

The double support period of the leg initially in stance includes peak hip extension, while the knee begins flexing in preparation for toe-off. Therefore, one explanation for the presence of elevated inappropriate quadriceps activity following stroke, is the misinterpretation at the spinal level of sensory (e.g., group I and II afferents) information originating from the hip proprioceptors, resulting in the production of spastic knee extensor activity. Sensory information from hip proprioceptors is known to be important in modulating stepping patterns following neurological insult (Grillner and Rossignol 1978; Hiebert et al. 1996). The fact that peak hip extension occurs during double support suggests that the stretch of the hip flexors may contribute to the presence of inappropriate uniarticular vasti activity. Multi-joint reflex responses involving
excitation of knee extensors have been reported previously in people with stroke. For example, common peroneal stimulation at group I and II strength elicits elevated early and late facilitation of quadriceps H-reflexes in patients with post-stroke hemiplegia as compared to unimpaired subjects (Marque et al. 2001; Maupas et al. 2004). This divergent excitation to muscles crossing different joints may result from increased excitability of propriospinal neurons following stroke (Mazevet et al. 2003). Despite these findings, the functional consequence of exaggerated multi-joint reflexes in the lower extremity following stroke is not well described.

In individuals with spinal cord injury, exaggerated multi-joint, heteronymous reflex responses are well known to contribute to abnormal muscle activation patterns. Specifically, lengthening the hip flexor muscles via passive hip extension movements elicits long-lasting hip flexor activity, with concomitant knee and ankle extensor activity (Schmit and Benz 2002; Steldt and Schmit 2004), which is consistent with the clinical description of an extensor spasm (Benz et al. 2005; Kuhn 1950; Little et al. 1989). Such data is in direct contrast to the well-established role of hip position afferents for facilitating limb flexion during terminal stance phase of locomotion in spinal or decerebrate cats (Grillner and Rossignol 1978; Hiebert et al. 1996), or infants during treadmill stepping (Pang and Yang 2000). The combined findings suggest a reorganization of heteronymous reflex function following neurological injury, which may increase knee extensor activity in response to hip extension. During gait, this reorganization of multi-joint reflex coupling between hip extension (as observed during terminal stance) and enhanced knee extensor activity may contribute to the commonly observed deficits in “stiff-legged gait”.

The presence of heteronymous stretch reflex activity from the hip flexors to knee extensors in subjects after stroke has not been demonstrated previously. Further, the contribution
of such heteronymous stretch reflex activity to abnormal gait kinematics in subjects with neurological injury has not been established. The purpose of this study was to examine the effect of an isolated imposed hip extension movement on knee extensor muscle activity in individuals with stroke and the potential relation of these heteronymous reflexes to kinematic abnormalities during gait. We hypothesized that the presence of increased quadriceps activity during and/or following an imposed hip extension movement is correlated to the presence of stiff knee gait (i.e., reduced knee flexion in swing).

Methods

Subjects

Twelve subjects (8 females, 4 males between 28 and 75 years old, mean = 52, SD = 11 years old) with chronic post-stroke hemiparesis (>6 months) were recruited for testing (Stroke group, see Table 1). Six of these subjects exhibited right side hemiparesis. All stroke subjects demonstrated clinical symptoms consistent with an ischemic or hemorrhagic unilateral brain lesion resulting in sensory motor dysfunction at least 6 months prior to testing. Subjects were excluded if they had a history of severe osteoporosis, cardiorespiratory diseases (e.g. cardiac arrhythmia, uncontrolled hypertension, chronic emphysema), unhealed decubiti, or significant residual cognitive or communication deficits that could impede the understanding of the purpose and procedures of the study. The individuals with stroke exhibited a variety of walking patterns yielding swing-phase knee flexion values that ranged from nearly “normal” to clinical stiff-knee gait. A group of 6 unimpaired control subjects (2 females, 4 males; age = 39 ± 10 years old) underwent identical reflex testing (Control group). All subjects were informed of the purpose
Reflex Testing and Analysis

Detection of the presence of hyperexcitable heteronymous stretch reflexes from the hip flexors to the uniarticular knee extensors was accomplished by imposing isolated hip extension movements using a Biodex System 3 (Biodex Medical Equipment, Shirley, NY). Evaluation of the role of passive hip movement on uniarticular knee extensor excitability began with the subject positioned in supine and the pelvis secured firmly to the table with a strap placed across the iliac crests to prevent pelvic rotation. The knee and ankle were fixed in a static posture by strapping the hemiparetic limb securely within a custom-designed, modifiable full-leg brace (Figure 1). The leg brace was fixed to the Biodex so that the motor’s axis of rotation was aligned with the flexion/extension axis of rotation of the hip. Proper alignment was verified visually by an absence of leg translation during manual movement of the leg brace, ensuring that observations of a muscle response about the knee were due solely to rotation at the hip.

The hip was rotated through a 50° excursion from flexion to extension, ending 1-2 degrees from maximum hip extension. The end range of motion was determined by the point at which the subject reported a muscle stretch in the upper thigh or by the tester noting a firm/muscular end-feel. All subjects denied the presence of pain or discomfort with the hip extension movement. The average start position for the Stroke group was 36 ± 6° of hip flexion, while the Control group began at an average of 30 ± 6° of hip flexion. The tested knee of both groups was fixed in approximately 10° of flexion, and the ankle was approximately 15° of plantarflexion. The knee was flexed to about 10° to approximately match the paretic knee’s position during the second double support period (prior to toe-off). Increasing knee flexion
would also increase the relative tension on the RF, and perhaps not elicit a sufficient stretch of
the uniarticular hip flexors (Van Dillen et al. 2000). The Biodex motor rotated the hip into
extension at 60, 90, and 120°/s to simulate a range of peak angular velocities observed during
normal gait (Granata et al. 2000). At the end of the imposed hip extension rotation, the limb was
held in the extended position for 5s before rotating back to the start (flexed) position.
Electromyographic measurement of rectus femoris (RF), vastus lateralis (VL), and vastus
medialis (VM) muscle responses was recorded using active surface electrodes (DE 2.1, Delsys
Inc., Boston, MA).

Fifteen trials were repeated at each tested velocity (i.e., 60, 90, and 120°/s) with
approximately 1 minute rest between trials. During the first 5 trials of each tested velocity,
subjects were asked to relax as much as possible during the imposed movement. The final 10
trials at each velocity were performed with the subjects pre-activating the hip flexors (including
the RF) at approximately 5-10% of their maximum voluntary isometric contraction (MVIC)
(Crago et al. 1976). This pre-activation level was maintained during the imposed hip extension
movement to ensure an adequate stretch of the hip flexors, and subjects were instructed to relax
several seconds following the end of the movement.

During all trials, the hip joint position, torque and velocity were recorded from the
Biodex. Simultaneous collection of EMG data occurred at 1000Hz, following amplification
(X10k) and band pass filtering between 20-450Hz. Analysis of muscle activity was performed
using custom designed software (LabVIEW 7, National Instruments, Austin, TX). A linear
envelope was created from the EMG data by full-wave rectifying the signals, and then filtering
with a phase-corrected, 8th order, low-pass Butterworth filter with a cutoff frequency of 10Hz.
The linear envelope was normalized to the peak recorded during a MVIC collected prior to
performing the reflex testing. The MVIC was performed while the subjects were seated (i.e., hip at approximately 70-80º and the knee flexed to approximately 10º), to allow for comparison of RF, VL, and VM muscle activity between groups. The normalized EMG for each muscle was combined into an ensemble average for the 5 relaxed trials, as well as for the 10 pre-activated trials, at each velocity. The individual muscle responses were compared between groups for each condition (i.e., relaxed and pre-activated).

Gait Testing and Analysis

All subjects in the Stroke group returned on a different day to undergo gait analysis to determine lower extremity kinematics during overground walking. Subjects did not use an ankle foot orthosis (AFO) during the gait testing session. As subjects walked across a 10m walkway, the motions of the lower extremity segments were tracked with a passive eight camera motion capture system (Motion Analysis Corp, Santa Rosa, CA) collecting at 120Hz. Joint centers were located by one inch (25.4 mm), retro reflective markers affixed to the posterior sacrum and bilaterally over the anterior superior iliac spines (ASIS), medial and lateral femoral condyles, and medial and lateral malleoli. Rigid thermoplastic shells, each with three markers firmly affixed, were attached to the lateral aspect of the thigh and shank and covered with an elastic wrap to minimize movement between the shell and the bone in order to track the limb segments during walking. The foot was tracked by markers placed on the posterior heel counter of the shoe and over the second metatarsal head. Subjects walked at their self-selected velocity, but were asked to maintain a consistent gait velocity across trials. The marker trajectories were low-pass filtered at 6Hz (EvaRT, Motion Analysis Corporation) to calculate the relative three-dimensional positions and inter-segmental joint angles using a rigid body analysis and
normalized to a stride cycle. (OrthoTrak 6.2.4, Motion Analysis Corporation) (Grood and Suntay 1983).

**Statistical Analysis**

Statistical analyses were performed with SPSS (SPSS 10.0, Chicago, IL). Outcome variables from the imposed hip extension movement (Figure 2) were calculated from the ensemble average of normalized EMG linear envelopes (Figure 3) and expressed relative to a baseline, identified as the average muscle activity during the 250ms period immediately prior to hip movement initiation. We were particularly interested in (1) the phasic reflex response, quantified as the initial peak reflexive response of the RF, VL, and VM muscles measured during the 150ms period immediately following the initiation of limb movement, and (2) the tonic or prolonged response, calculated as the difference in EMG magnitude between the baseline average (250ms prior to hip movement) and the final position average in muscle activity (identified as the 250ms immediately following termination of hip extension). Analyses were performed during both relaxed and pre-activated conditions. Group means and standard deviations of muscle activity were compared using a 2-way (group by imposed hip velocity) repeated measures ANOVA (repeated for imposed hip velocity). If differences were found to be significant, Bonferroni corrected post hoc testing was performed. Gait kinematic variables included mid-stance peak hip extension and swing phase peak knee flexion angles, as well as the peak hip extension velocity and the knee flexion velocity at toe off. Paired t-tests were used to compare kinematic variables between limbs. Finally, Pearson product moment correlations were used to relate peak initial and prolonged reflex responses to gait kinematics (i.e., peak knee flexion during swing and knee flexion velocity at toe off). All statistical tests were 2 sided and a significance level of $p < 0.05$ was used.
Results

Reflex Responses

Following the initiation of the imposed hip movement, the stretched RF muscle as well as the unstretched VL and VM exhibited a brief reflexive response followed by a sustained EMG signal that was particularly evident in the Stroke group, as demonstrated in Figure 3. The quadriceps response to the hip extension movement was generally larger in the Stroke group than the Control group during both the relaxed and pre-activated conditions. In addition, the quadriceps reflex responses were generally larger during the pre-activated trials compared to the relaxed trials.

Relaxed trials:

During the relaxed trials, small amplitude reflex responses were observed in both Stroke and Control groups. An analysis of the initial peak reflexive response revealed a significant main effect for imposed velocity for the VL (ANOVA: p<0.005), however a significant velocity X group interaction (ANOVA: p<0.05) suggested that the groups did not respond similarly. Post-hoc testing related to VL muscle activity demonstrated that the Stroke group exhibited a significantly greater peak than the Control group at 90°/s (p<0.05) and 120°/s (p<0.01) although no difference was observed between the groups at 60°/sec (p=0.56). Despite non-significant main effects for group for the peak responses of the RF (ANOVA: p=0.06) and VM (ANOVA: p=0.30) (Figure 4A), the Stroke group exhibited larger responses on average with group differences ranging from 0.9 – 5.1 %MVIC for the RF, and 0.1 – 4.0 %MVIC for the VM, depending on the test velocity.
In addition to the observed initial reflexive responses, prolonged muscle activity was also seen in the tested muscles. In general, the magnitude of reflex EMG activity in the Stroke group remained elevated following the imposed movement, while the Control group’s muscle activity did not. Specifically, the VL exhibited a significant main effect for group (ANOVA: p<0.05), revealing greater prolonged VL activity in the Stroke group compared to the Control group (Figure 4B). Likewise, the RF exhibited a significant main effect for group (ANOVA: p<0.05) and imposed hip velocity (ANOVA: p<0.05), as well as a significant group X velocity interaction (ANOVA: p<0.05). Post-hoc tests revealed that the RF of the Stroke group was significantly greater than the Control group at all tested velocities (60°/s: p<0.05; 90°/s: p<0.01; 120°/s: p<0.005). No group differences were observed in the prolonged response of the VM muscle (ANOVA: p=0.07) although the Stroke group exhibited a 0.6 – 1.6 %MVIC greater response than the Control group, depending on the imposed velocity.

**Pre-activated trials:**

Subjects pre-activated the hip flexors prior to the imposed hip movement. No difference in pre-activation level was observed between groups for the VL (p=0.36), RF (p=0.28) or VM muscles (p=0.19). With the hip flexors pre-activated to 5-10 %MVIC, larger magnitude initial peak reflex responses were observed in the Stroke subject’s RF (p<0.001), VL (p<0.01), and VM (p<0.01) muscles compared to the relaxed condition (Figure 2). Additionally, the RF’s prolonged activity (p<0.05) was significantly greater during the pre-activated trials compared to the relaxed condition although the VL (p=0.07) and VM (p=0.15) did not significantly increase with the hip flexors pre-activated.

The magnitude of the Stroke group’s initial peak reflex response was generally observed to be larger than that of the Control group. Overall, there was a significant velocity X group
interaction effect for the VL (ANOVA: p<0.05) and RF (ANOVA: p<0.05) muscles, suggesting that the Stroke and Control groups responded to the imposed hip perturbation at different velocities in a different manner (Figure 4C). Specifically, the Stroke group’s initial reflex response was strongly velocity dependent for the VL (ANOVA: p=0.001), RF (ANOVA: p<0.001), and VM (ANOVA: p<0.001) muscles, whereas the Control group exhibited a velocity dependent response for the VL only (ANOVA: p<0.005). As such, the difference in the response magnitude between groups was accentuated at greater imposed velocities. At the two slowest test velocities (60 and 90°/s), no significant differences were observed between the groups for any recorded muscles (group differences ranged from 2.1 – 10.7 %MVIC). However, for the fastest velocity (120°/s), all tested muscles (VL: p<0.01; RF: p<0.05; VM: p<0.05) exhibited a significantly greater initial response in the Stroke group compared to the Control group.

Similar to the relaxed condition, a prolonged facilitation in muscle activity was observed in the Stroke group following hip extension with the hip flexors pre-activated. A significant main effect for group was observed for the VL (ANOVA: p=0.005) and RF (ANOVA: p<0.001) muscles, revealing that the long lasting EMG activity observed in the Stroke group was significantly greater than that of the Control group for these muscles. Although no group difference was observed for the VM (ANOVA: p=0.09) muscle, the trend was similar to the responses of the VL and RF (Figure 4D). The imposed test velocity had no significant effect on the magnitude of the prolonged reflex response for any of the tested muscles (all p values > 0.50).

Gait Kinematics
The subjects with stroke walked at an average of 0.6 ± 0.3 m/s. During overground gait, differences in peak stance-phase hip extension between paretic (-8.4 ± 9.1°) and nonparetic limbs (-11.4 ± 8.2°) was not significant (p=0.19) (Figure 5A). In addition, no difference was observed between the paretic limb’s peak hip extension (-8.4 ± 9.1°) during walking and the hip extension imposed by the Biodex motor during reflex testing (-13.6 ± 6.1°; p = 0.18). Angular hip extension velocity was, however, slower on the paretic (49 ± 21°/s) vs. nonparetic side (73 ± 29°/s; p<0.05) during walking. During swing, the subjects flexed the paretic knee to 28 ± 15°, which was significantly less than the nonparetic peak knee flexion of 64 ± 8° (p<0.001) (Figure 5B). The individuals with stroke also flexed their hip significantly less during swing phase on the paretic side (23 ± 9°) compared to the non-paretic side (36 ± 10°; p<0.001). No significant relationship was observed between the peak hip flexion angle and the peak knee flexion angle during swing (R = 0.44; p = 0.15). Knee flexion velocity at toe off was also significantly reduced on the paretic side (163 ± 92°/s) compared to the nonparetic side (259 ± 93°/s; p<0.001). The knee flexion velocity at toe off correlated significantly with the peak knee flexion angle during swing (R=0.87, p<0.001).

Correlation of Reflex Measures and Gait Kinematics

Paretic knee kinematics were correlated to the muscle responses observed following an isolated imposed hip extension movement. Because the individual muscle’s prolonged responses were correlated to each other (R values between 0.68-0.86), the sum of the prolonged responses of the quadriceps muscles (VL+RF+VM) was used as the independent variable for the correlation with kinematic measures. The sum of the prolonged responses of the pre-activated VL, RF, and VM was significantly correlated to swing-phase peak knee flexion angle and the
strength of the relationship improved with higher test speeds (60°/s: R= -0.70, p<0.05; 90°/s: R= -0.75, p<0.005; 120°/s: R= -0.79, p<0.005) (Figure 6). Likewise, the sum of the prolonged response of the pre-activated VL, RF, and VM muscles was negatively related to knee flexion velocity at toe off (60°/s: R= -0.63, p<0.05; 90°/s: R= -0.76; p<0.005; 120°/s: R= -0.75; p<0.005) (Figure 7). In addition, the sum of the prolonged response of the pre-activated quadriceps muscles elicited at 90°/s was negatively related to the peak hip extension velocity (R= -0.56; p=0.05) during walking, although the responses elicited by the 60°/s (R= -0.18; p=0.57) and 120°/s (R= -0.52; p=0.08) hip movements were not (Figure 8). Although the prolonged response of the quadriceps during isolated testing was significantly related to the impaired limb’s movement pattern during walking, the initial peak reflexive response was not related to the peak knee flexion angle at any tested velocity (all p values>0.20). In addition, initial peak and prolonged reflex responses were not correlated to peak hip extension angle or gait speed.

Discussion

These data demonstrate that an imposed hip extension movement contributes to heightened, long-lasting quadriceps muscle activity in individuals with stroke that is correlated to knee kinematics during walking. These results provide insight into the potential mechanisms accounting for “spastic stiff-legged gait” including the possible role of heteronymous reflexes from hip flexors onto knee extensors.

Role of Heteronymous Reflexes in Spastic Gait
The heightened response of the uniarticular knee extensor muscles (i.e., VL and VM) to an imposed hip movement suggests the presence of multi-joint, heteronymous excitatory reflexes from the hip proprioceptors to the knee musculature. Given the RF’s anatomical position as a hip flexor and knee extensor, it is tempting to attribute the uniarticular vasti’s response to a stretch of the biarticular RF alone. In an analogous situation, however, group I afferents from the biarticular gastrocnemius muscle do not facilitate the uniarticular soleus muscle (Mao et al. 1984). Additionally, hip position afferents from numerous hip muscles are known to mediate lower extremity responses (Kriellaars et al. 1994), providing substantial redundancy in the sensorimotor system, suggesting that hip afferents from muscles other than the RF contribute to the initiation of the vasti’s response. Descriptions of multi-joint reflexes in animal models are pervasive in the literature, (Nichols 1999) in addition to a recent report of a group II-mediated, excitatory connection between the ankle and knee musculature in unimpaired humans (Marchand-Pauvert et al. 2005). In comparison, individuals with stroke are well known to exhibit elevated single joint reflex responses (i.e., spasticity (Lance 1980)), and more recently have revealed augmented heteronymous reflex responses between the ankle and knee (Marque et al. 2001; Maupas et al. 2004). Heteronymous reflex activity between the hip and knee joints, however, has not been described previously in unimpaired subjects or individuals with stroke, although individuals with spinal cord injury demonstrate analogous behaviors (Schmit and Benz 2002). The current results suggest similar, abnormal hip-knee reflex coupling between those with SCI and those with stroke, which may be related to spinal reflex reorganization following injury to the descending tracts.

**Origin of Enhanced Multi-joint Reflexes in People with Stroke**
The multi-joint reflexes observed in the current study were characterized by both an early velocity-mediated component and a prolonged component that was not velocity mediated and which persisted beyond the duration of the hip movement. The velocity-dependence of the initial response is consistent with classically defined spasticity about a single joint (Lance 1980) and suggests a response to the hip flexor’s velocity-sensitive (group Ia) muscle spindle activity. However, both single-joint spasticity (Nadeau et al. 1999a) and the early velocity-mediated component of the heteronymous reflex responses described here have questionable roles in the performance of functional tasks (Patten et al. 2004), in particular, locomotion (see however, Damiano et al. 2006)). In contrast to the early component, the prolonged reflex component was not velocity mediated, and was highly correlated to knee kinematics in the Stroke group.

Although group I and II hip afferents likely contribute to the initiation of the early component of the reflex response, the precise neurophysiological mechanisms underlying the prolonged reflex responses to an imposed stretch are less clear. An increased reflex excitability of the group II pathways could have accounted for the larger prolonged reflex response in the Stroke group. Both test groups were exposed to a similar hip flexor perturbation and thus similar peripheral input (e.g., group II) during the static hold, however, the groups responded differently to the imposed stretch of the hip muscles. Because peripheral inputs were assumed to be similar, differences in modulation at spinal/supraspinal levels likely contributed to differences in motor output. Although group II afferents likely contributed to the prolonged response, the long-lasting knee extensor activity in the individuals with Stroke may not be accounted for solely by group II afferent input. While the excitatory drive from the group II afferents remains elevated during the hold portion, the discharge rate of the secondary endings diminishes during the static portion of a
ramp-hold perturbation (Fischer and Schafer 2000) suggesting that other mechanisms may contribute to the long-lasting knee extensor activity as well.

Another explanation for the prolonged muscle activity following stretch is the presence of non-linear, ionic currents in spinal interneurons and/or motoneurons, which can both amplify and prolong motor output following brief afferent inputs (Kiehn and Eken 1998). The persistent inward currents that underlie the long-lasting depolarization and discharge (i.e., plateau potentials) of these spinal neurons are often facilitated by descending serotonergic and noradrenergic inputs from brainstem (reticular) nuclei. The presence of prolonged motor outputs following a brief synaptic input has previously been observed in humans without neurological injury (Kiehn and Eken 1997) as well as in individuals with SCI (Gorassini et al. 2004; Hornby et al. 2006; Hornby et al. 2003). Similar responses have likewise been observed in decerebrate animal preparations (Crone et al. 1988; Hounsgaard et al. 1988), which, much like a cortical stroke, have the potential for disinhibition of the brainstem. Such a disinhibition may facilitate modulation of α-motoneurons or low threshold spinal interneurons (Hammar et al. 2004) to generate long-lasting motor activity indicative of underlying persistent inward currents. Further neurophysiological testing is certainly required to investigate the potential contributions of these currents to abnormal motor strategies following stroke.

Role of Reflexive Knee Extensor Activity in Walking

The presence of exaggerated heteronymous reflex activity between hip flexors and knee extensors in individuals with stroke may have important functional consequences. In particular, the heightened quadriceps muscle responses that persist following hip extension were correlated with reduced knee flexion velocity at toe-off as well as the peak knee flexion angle attained.
during the swing phase of walking. Although this correlation does not imply “cause and effect”, it provides evidence that the quadriceps response to isolated hip extension appears to be related to knee kinematics during walking. The time spent in the double support period at the end of the paretic limb’s stance phase for the subjects in this study was 223±86ms. This corresponds well to the 250ms time chosen to evaluate the prolonged reflex response to imposed hip movements and indicates that the muscle activity we observed in an isolated setting could have a direct impact on the specific phase of the gait cycle purported to be crucial to attaining sufficient knee flexion. A potential limitation, however, is that if there is a critical amount of hip extension required to elicit the quadriceps response and that threshold was achieved in supine, but not in walking, then the reflex would not contribute to decreased swing phase knee flexion. The amount of hip extension during walking and the reflex testing, however, were not significantly different (p = 0.18), but additional work will need to be performed to establish if such a critical amount of hip extension exists to trigger the quadriceps activity. It was also observed that the hip extension velocity during walking was inversely related to the magnitude of the quadriceps responses triggered by faster imposed hip movements. Peak hip extension occurs in late stance, during the double support phase of the leg initially in stance. Although the knee joint normally flexes during this period in unimpaired individuals, even small increases in vasti activity during double support can produce substantial reductions in knee flexion velocity, the marker for subsequent swing phase knee flexion (Goldberg et al. 2004). A potential limitation of our data is that we did not record quadriceps EMG from the Stroke group during the walking analysis. While this may potentially limit our interpretation of the data, there is ample evidence to demonstrate that the rectus femoris and the vasti are overactive during terminal stance/early swing (Kerrigan et al. 1991; Remy-Neris et al. 2003; Sung and Bang 2000; Waters et al. 1979).
The results presented here suggest a possible neurophysiologic mechanism to explain this overactivity, although future research is certainly warranted to confirm this hypothesis. Additionally, it is certainly possible that other impairments in muscle function may also contribute to the observed reduction in swing phase knee flexion.

Although overactivity of the quadriceps muscle is often assumed to be the cause of stiff-knee gait, the mechanical coupling between the joints of the leg suggests that alterations in muscle function at other joints in the lower extremity also influence knee flexion during swing. For instance, there has been evidence that reductions in either hip and/or ankle moments at toe-off limit subsequent swing phase knee flexion (Goldberg et al. 2004; Kerrigan et al. 1998; Olney and Richards 1996; Piazza and Delp 1996). At the ankle, both overactivity of the soleus muscle (Neptune et al. 2001) or inadequate ankle power generation at toe-off (Kerrigan et al. 2001) are thought to lead to reduced swing phase knee flexion. The contribution of these variables to the decreased swing phase knee flexion observed in this study is not known. It is possible that these variables, in addition to the heightened reflex response of the quadriceps, substantially contributed to decreased swing phase knee flexion.

Others have noted that strong hip flexion can adequately compensate for the diminished push-off at the ankle (Nadeau et al. 1999b), however, reduced hip flexor moments have been tied to diminished swing phase knee flexion (Olney and Richards 1996; Piazza and Delp 1996). It is possible, then, that decreased hip flexion was a factor in the decreased swing phase knee flexion observed in the present study. Despite this prior evidence, peak hip flexion and peak knee flexion angles during swing were not related in our Stroke group. Clearly, however, there are many potential mechanisms, in addition to reflex coupling of the hip and knee reported here, that may contribute to the stiff-knee gait pattern often seen following stroke. Future studies should
address the importance of each of these potential mechanisms and attempt to understand how these mechanisms may differ in sub-groups of the post-stroke population.

The observation that pre-activation of the hip flexor muscles (with RF) facilitate the RF reflex response to imposed hip extension may also have implications for gait. During swing initiation, flexion of the leg is driven, in part, by activation of the hip muscles, which occurs near peak hip extension. Despite the RF’s anatomical position as a hip flexor, emerging evidence suggests that activation of the RF muscle will actually accelerate the hip into extension via dynamic coupling with the knee (Hernandez et al. 2007; Neptune et al. 2004). As a hip extensor, we speculate that the presence of increased RF activity may actually contribute to a reduction in hip flexion around toe-off (Kerrigan et al. 2001). Additionally, the presence of RF activity during both terminal stance of walking (Waters et al. 1979) and during the pre-activated condition of our reflex testing suggests that we are producing comparable behaviors. The fact that hip flexion (with activation of the RF) facilitates the inappropriate prolonged RF activity in an isolated setting may prompt individuals with stroke to unconsciously reduce the net hip flexor moment during walking. Such a strategy may be ineffective, however, in increasing knee flexion, because a larger hip flexor moment is thought to be important for facilitating knee flexion during swing (Kerrigan et al. 1998). In addition, some individuals with stroke need to increase hip flexion moments to compensate for plantarflexor weakness (Nadeau et al. 1999b).

Such an increase in hip flexor activation, however, appears to augment the reflex excitability of the RF under isolated settings. Inappropriate knee extensor activity, initiated by hip extension and facilitated by hip flexor activation prior to swing, may therefore provide a neurophysiological basis for the commonly observed kinematic walking impairments in subjects with stroke.
A potential limitation to the current results is that different head/trunk orientations were employed for the acquisition of heteronymous reflexes (e.g. supine) and the gait analysis (e.g., upright). The vestibular system’s influence on spinal circuitry may therefore be altered, affecting both volitional (Lewek et al. 2006) and reflex activity (Rossi et al. 1988; Trimble 1998). Specifically, extensor circuits appear to be inhibited with the body in supine relative to an upright posture (Lewek et al. 2006; Rossi et al. 1988; Trimble 1998). During an upright task such as walking, the magnitude of the reflex response has the potential to be augmented beyond what was observed in supine. Other influences, such as a prolonged load through the limb are also known to suppress extensor pathways in the lower leg, (Trimble 1998) although load-release, (e.g., toe-off) can further increase knee extensor activity (Wu and Schmit 2006). Thus, any response observed in a supine, unloaded condition appears to convey an underestimation of extensor reflex activity compared to what might be observed during gait. Nevertheless, because all subjects in both groups experienced the same postures, the strength of the relationship between the observed reflex response and kinematics during gait should remain fundamentally unaffected.

The current data suggest an important reorganization of the reflex regulation which may influence gait following stroke. Although others have emphasized the importance of attaining hip extension during terminal stance to maximize subsequent hip flexion following neurological injury, (Behrman et al. 2005) our data suggests that concomitant knee extensor activity may be triggered as a result of a rapid hip extension movement.
Acknowledgments:

The authors acknowledge Theresa Hayes, MS, Jennifer Moore, MPT, and Heidi Roth, MSPT for valuable assistance with data collection and subject recruitment. The authors thank Vicki Mercer PT, PhD for her critical review of this manuscript.

Funding provided by the American Heart Association, the National Institutes of Health (5T32HD007418), and the National Institute on Disability and Rehabilitation Research (H133G040065).
References


Figure Legends:

1. Subject setup in supine. The hip is rotated into extension while the knee and ankle are held static.

2. Example of muscle responses for a Control (left) and Stroke subject (right) during a “pre-activated” trial.

3. Variables obtained during reflex trials: Top trace represents hip extension movement, while the bottom three traces represent the ensemble average of the linear envelope of RF, VL, and VM. The peak response is chosen within 150ms of the initiation of movement (dark gray). The prolonged response is the difference in averaged activity from pre- to post-movement (light gray).

4. Group means and standard deviations for the initial peak reflexive response for (A) relaxed and (C) pre-activated trials for the Control and Stroke groups at 60, 90, and 120°/s. The prolonged response followed the initial peak response. Group means and standard deviations for the prolonged response for the (B) relaxed and (D) pre-activated trials for the Control and Stroke groups at 60, 90, and 120°/s.

5. Sagittal plane hip (A) and knee (B) kinematics for the Stroke group’s paretic (dashed) and nonparetic sides (solid±1SD).

6. Relationship between swing phase peak knee flexion angle and prolonged response of the VL, RF, and VM muscles during “pre-activated” trials at (A) 60°/s, (B) 90°/s, and (C) 120°/s.

7. Relationship between knee flexion velocity at toe-off and the prolonged response of the VL, RF, and VM muscles during the “pre-activated” trials at (A) 60°/s, (B) 90°/s, and (C) 120°/s.
8. Relationship between peak hip extension velocity (deg/seg) and prolonged response of
the VL, RF, and VM muscles during “pre-activated” trials at (A) 60°/s, (B) 90°/s, and (C)
120°/s.
<table>
<thead>
<tr>
<th>Subject</th>
<th>Age</th>
<th>Lesion location</th>
<th>Time since stroke (mos)</th>
<th>Berg Balance Score</th>
<th>Comfortable gait speed (m/s)</th>
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<tr>
<td>S1</td>
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<tr>
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<td>Left hemisphere</td>
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<tr>
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<tr>
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<td>Left hemisphere</td>
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<tr>
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<tr>
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<tr>
<td>S9</td>
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<td>Left posterior insula and putamen, ischemic</td>
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<td>47</td>
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<tr>
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<td>59</td>
<td>Right hemisphere</td>
<td>51</td>
<td>52</td>
<td>0.52</td>
</tr>
<tr>
<td>S12</td>
<td>28</td>
<td>Right hemisphere, hemorrhagic</td>
<td>10</td>
<td>55</td>
<td>0.57</td>
</tr>
</tbody>
</table>
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116x180mm (300 x 300 DPI)
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